

# A Framework for Scalable Trainable Image-based Query in Video

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Informedia-II  
*Carnegie Mellon University*



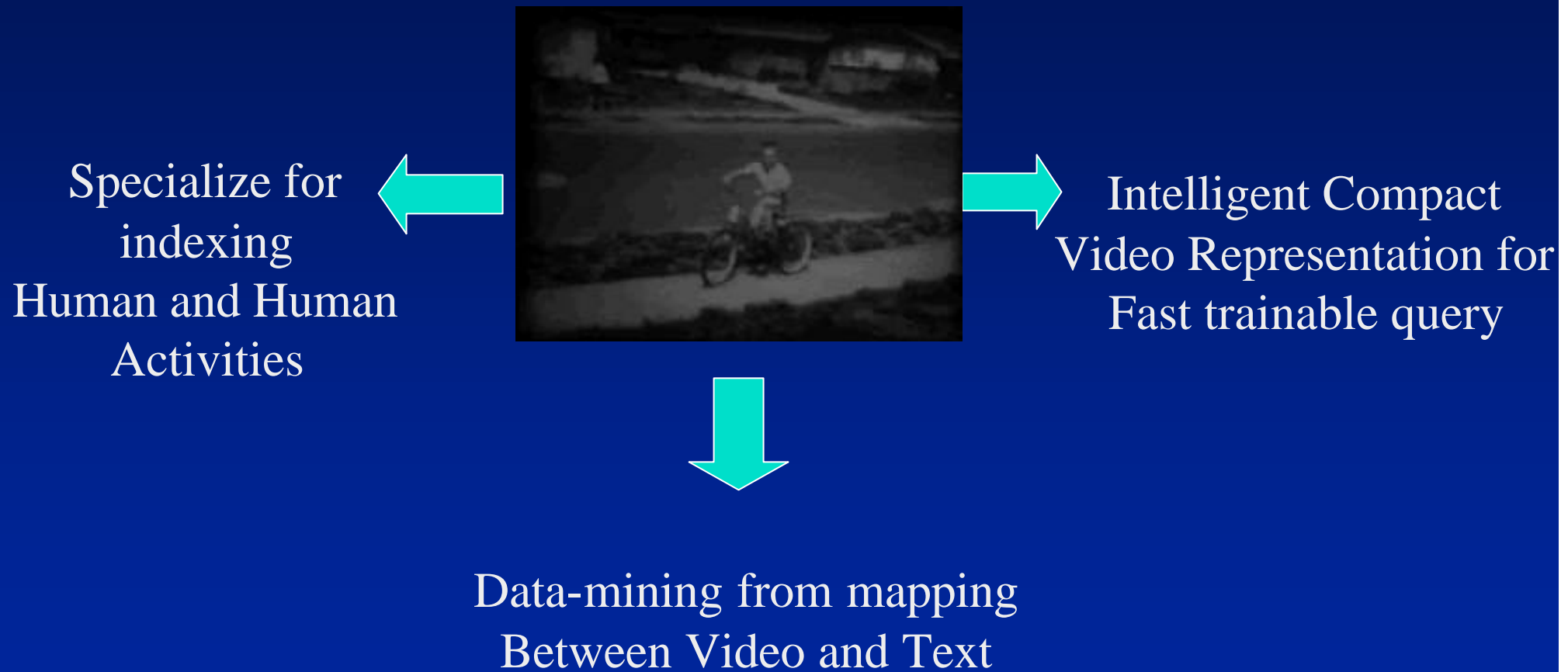
- Multi-modal query of video
  - Speech recognition
  - Text analysis
  - Object detection in video
- Visualization and Summarization
  - Multiple Video Documents
  - Topic collages

<http://www.informedia.cs.cmu.edu>



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  - Informedia-I, Blobworld, QBIC, ect.

- Image-based query is a powerful tool for finding relevant information
  - Informedia-I, Blobworld, QBIC, ect.
- ...but we are far from achieving
  - Human level object recognition
  - Rapid processing of massive video/image data
    - *The story is in the large of volume data*





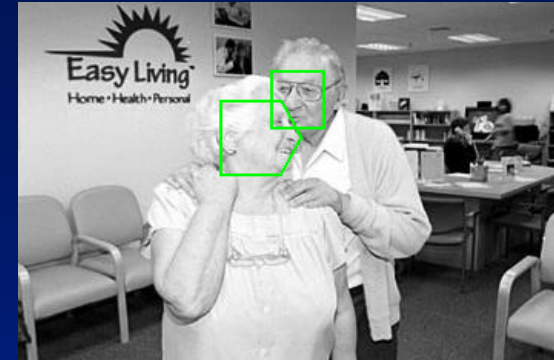
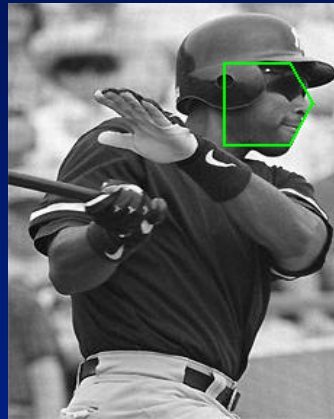
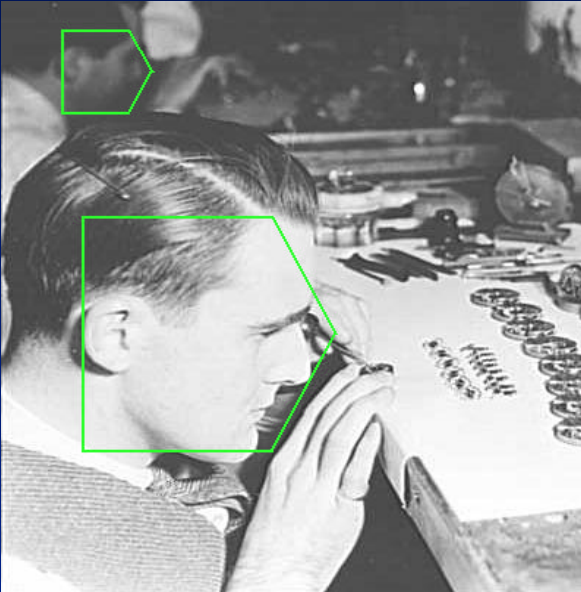
Human Identity: Face

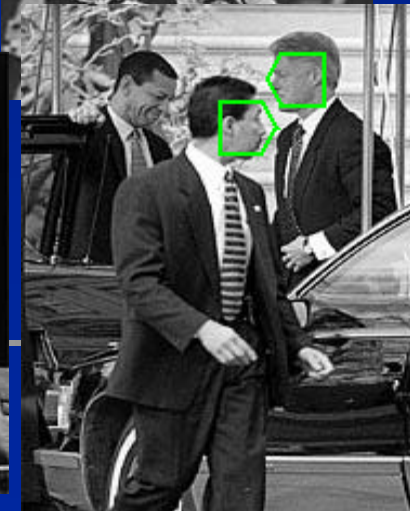
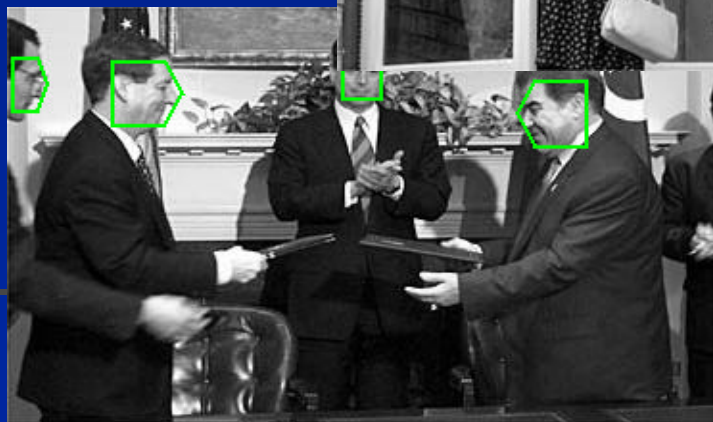
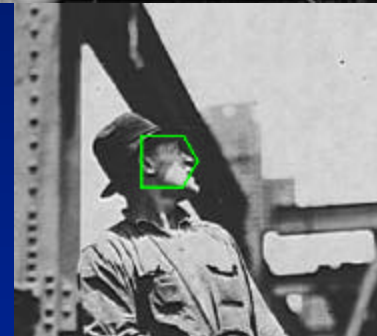
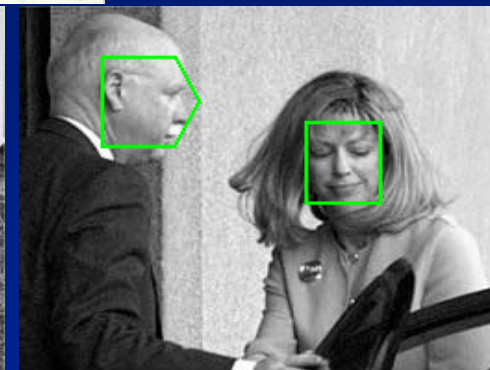
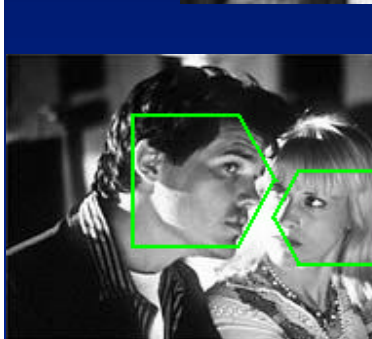
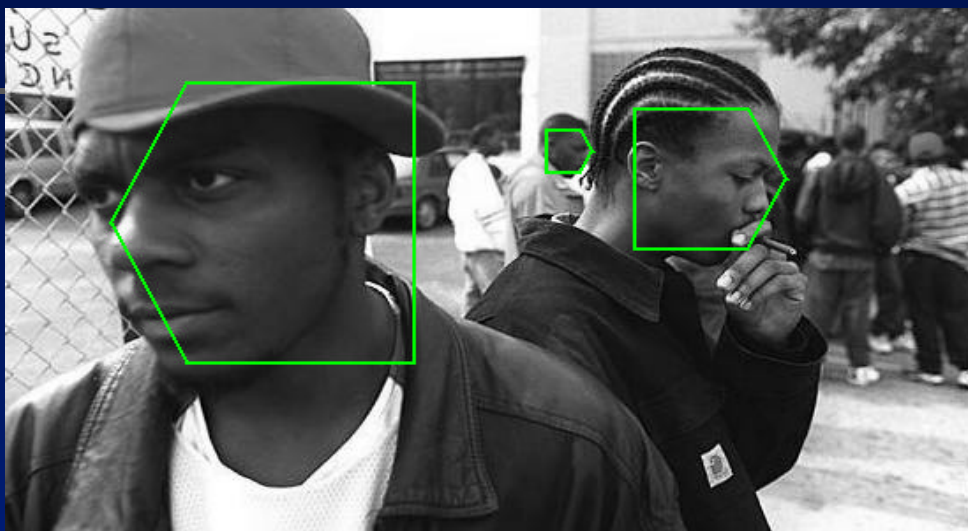


Human Activity Recognition: Body



Face Detection - Henry Schneiderman (CMU)





Detecting detecting human in video

Understanding human activity

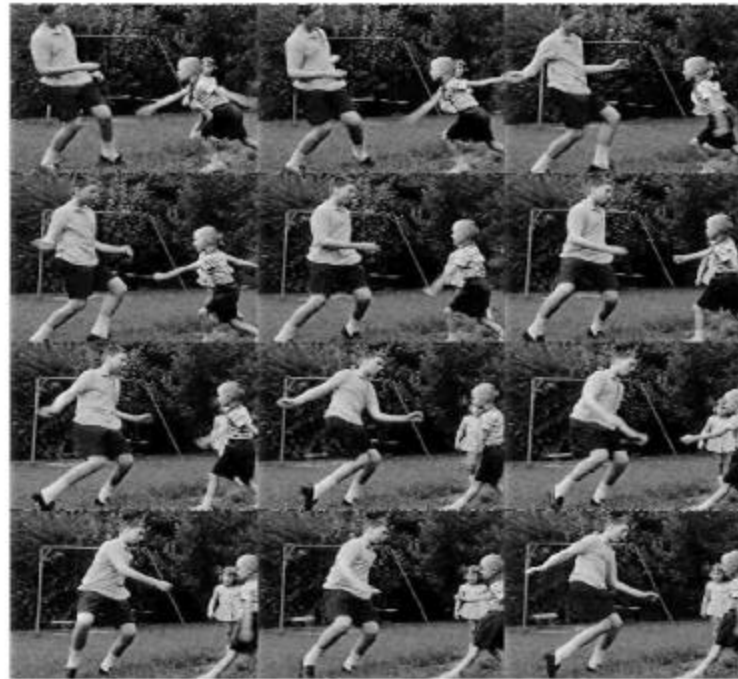
Measuring/analyzing body movement

Recognizing human from body movement



## The main difficulty:

11

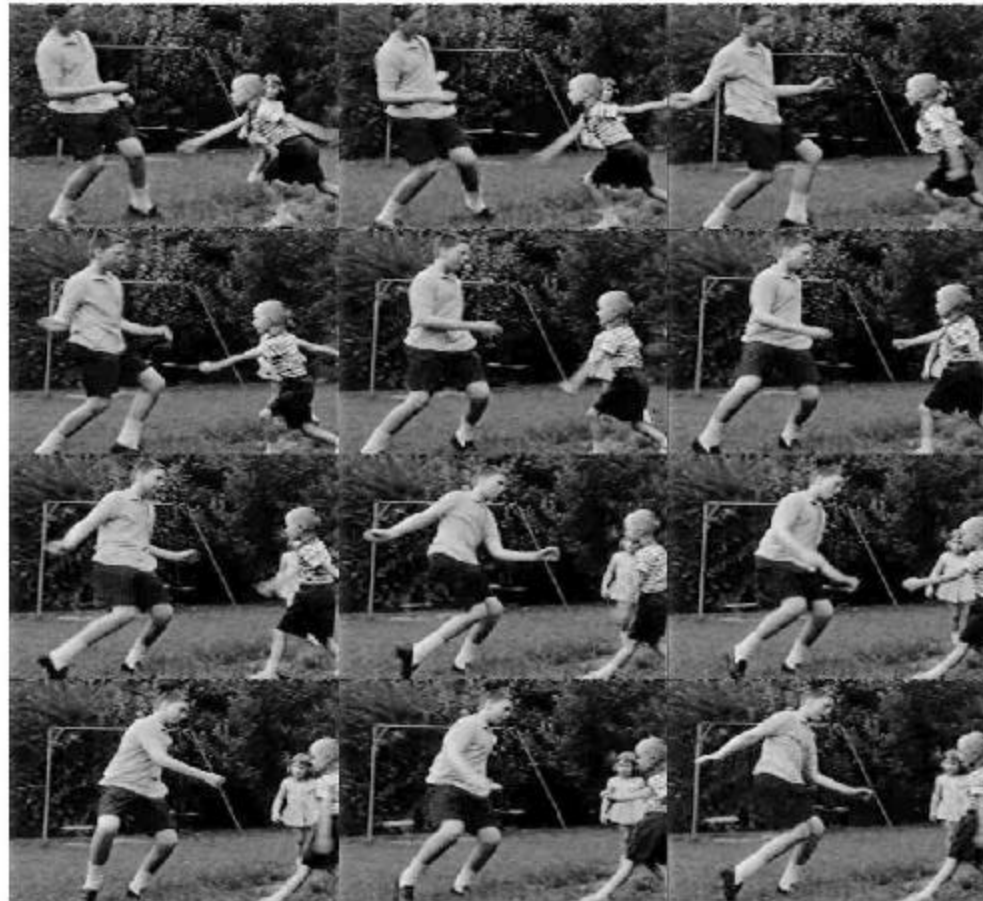


$$N = (npixel \times num\_orientation \times num\_scale)^{body\_parts}$$
$$= (10^6 \times 10^2 \times 5)^9 = 6 \times 10^{78}!$$

- Controlled setting: background subtraction
- Hand initialization, user assisted tracking
- Grouping based body detection:
  - Forsyth, Finding Naked Body, ECCV'96
  - Felzenszwalb, Huttenlocher, ICCV'99

## Body finding in a video:

13



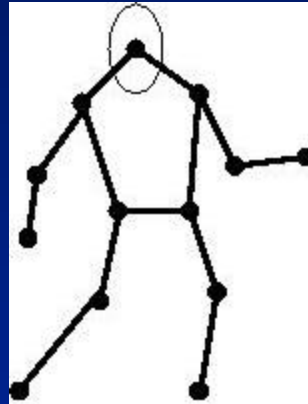
- Using motion information to find possible locations of joints,
- Using MRF inferencing technique for finding the globally optimal body configuration.

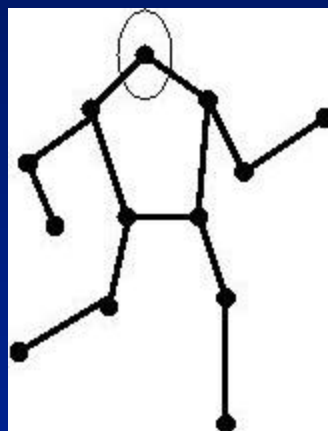
## Joint location from motion field

15



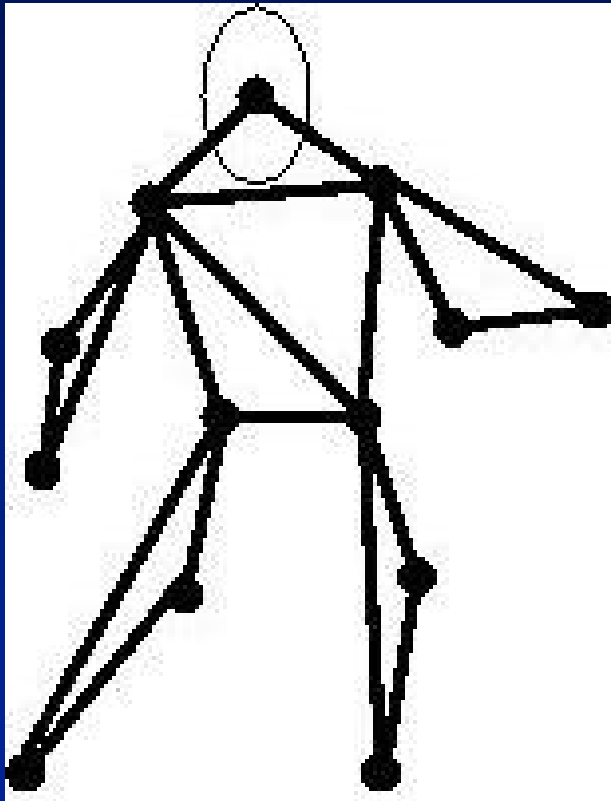
94, 3E = -92 0000





## Body joint tree:

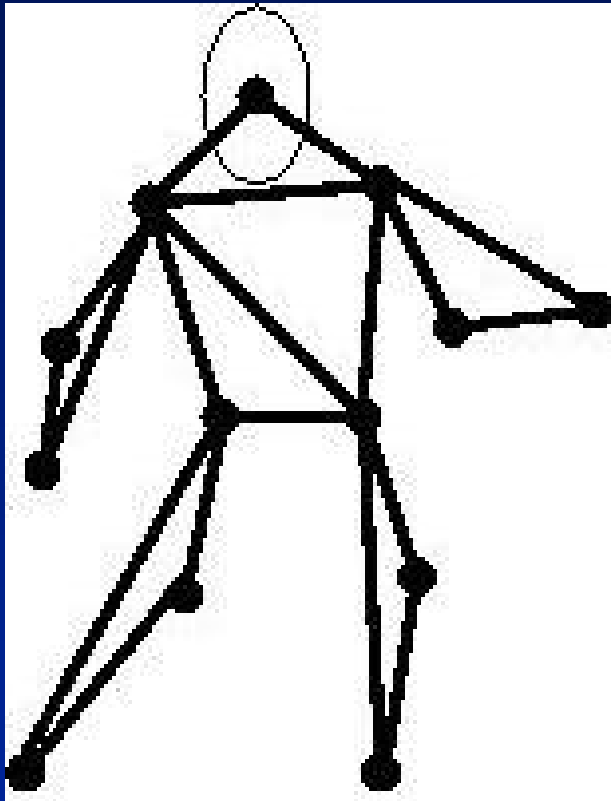
18



Let  $L = (l_1, l_2, \dots, l_n)$ , be the assignment of each joints

$$E(L) = \sum_{(l_i, l_j, l_k)} E(l_i, l_j, l_k) + \sum_{l_i} E(I, l_i),$$

$$P(L) = \frac{1}{Z} e^{-E(L)}$$



$$E(L) = \sum_{(l_i, l_j, l_k)} E(l_i, l_j, l_k) + \sum_{l_i} E(I, l_i),$$

$E(I, l_i)$  = how likely  $l_i$  is a joint,

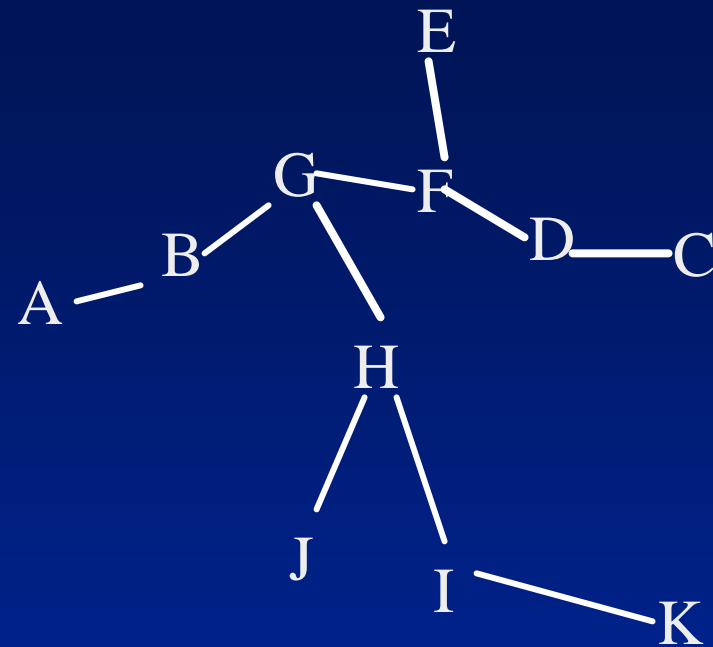
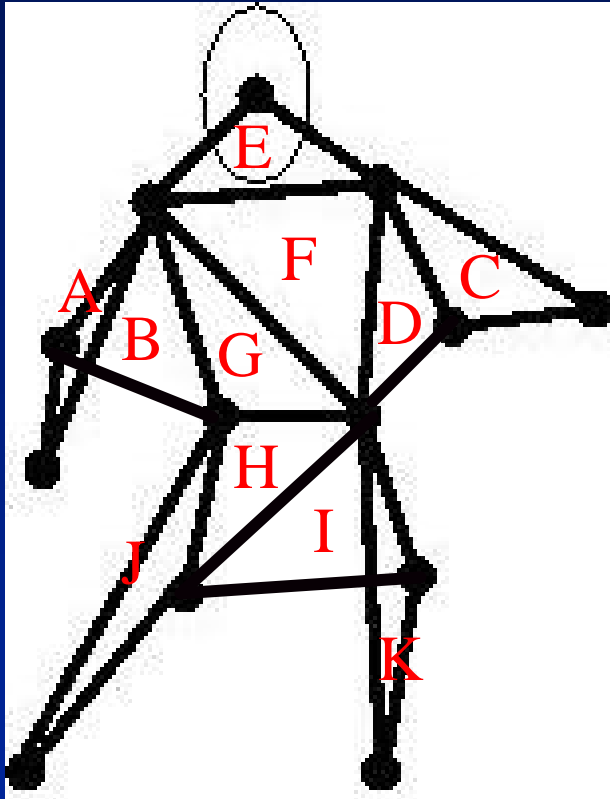
$E(l_i, l_j, l_k)$  = how likely is this configuration of three joints.

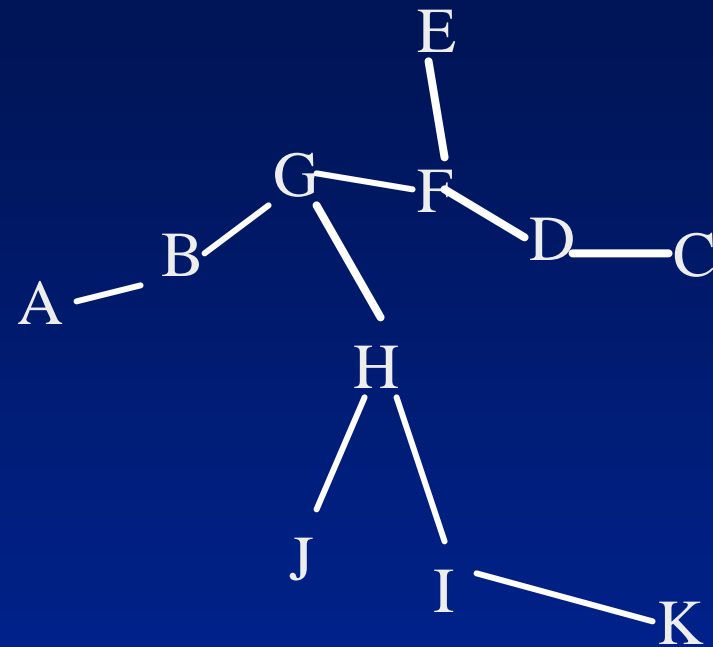
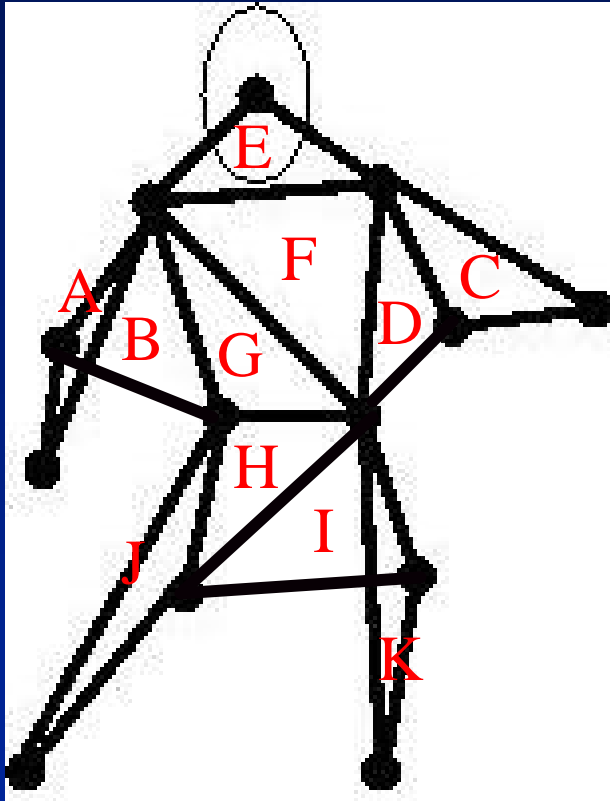
Depends on :

- 1) geometrical relationship,
- 2) relative motion,
- 3) image information.

# Clique tree

20

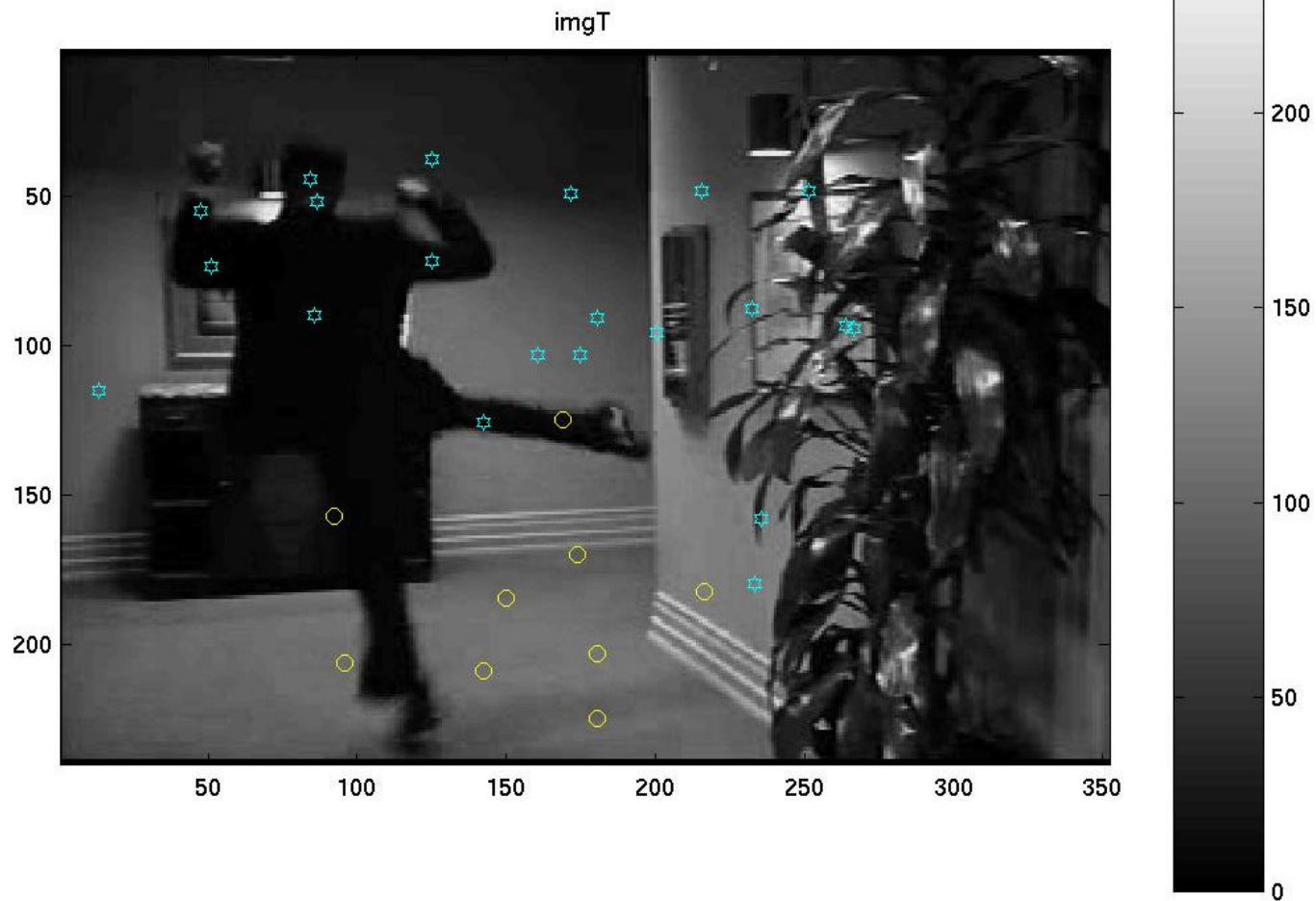




Run Dynamic programming on  
the clique tree above

## Possible body-part locations:

22

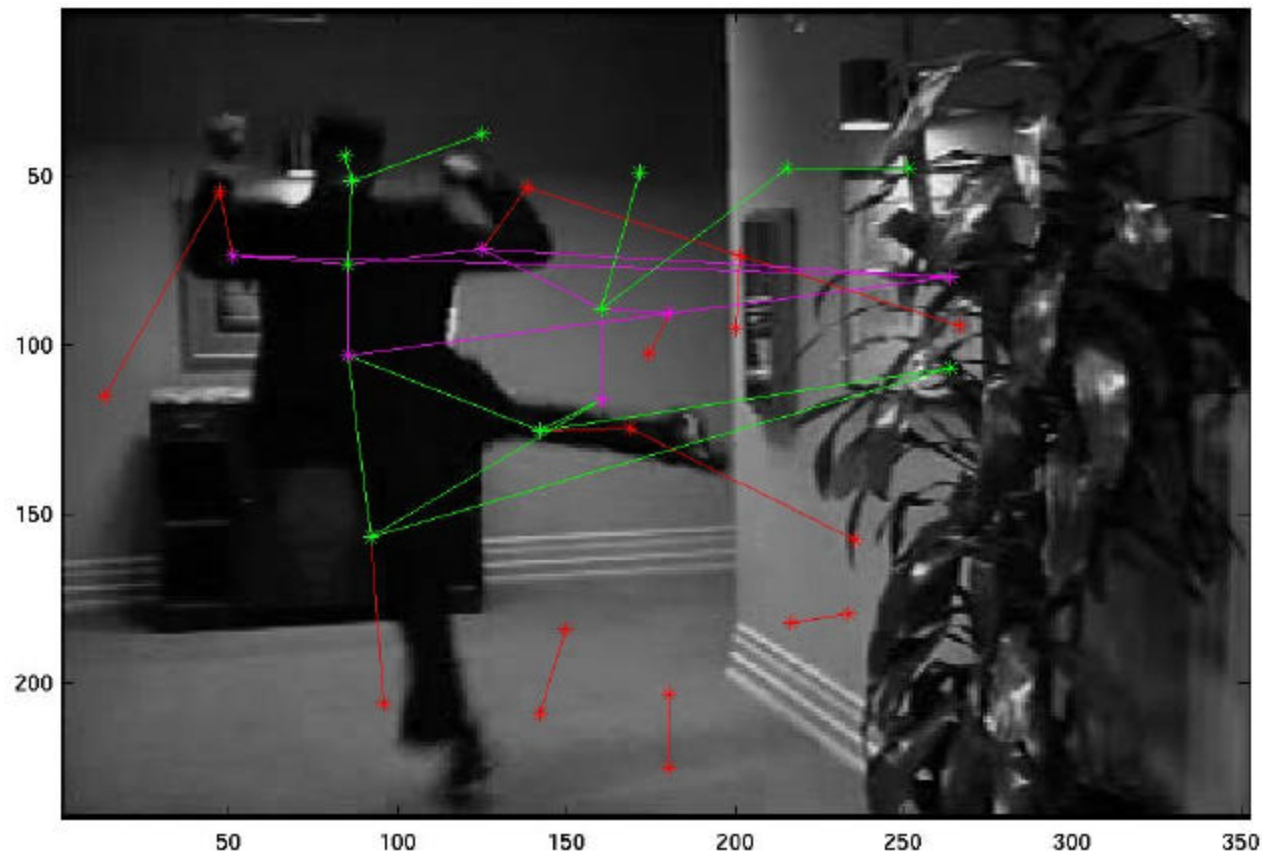


8, 119 = 87.0000



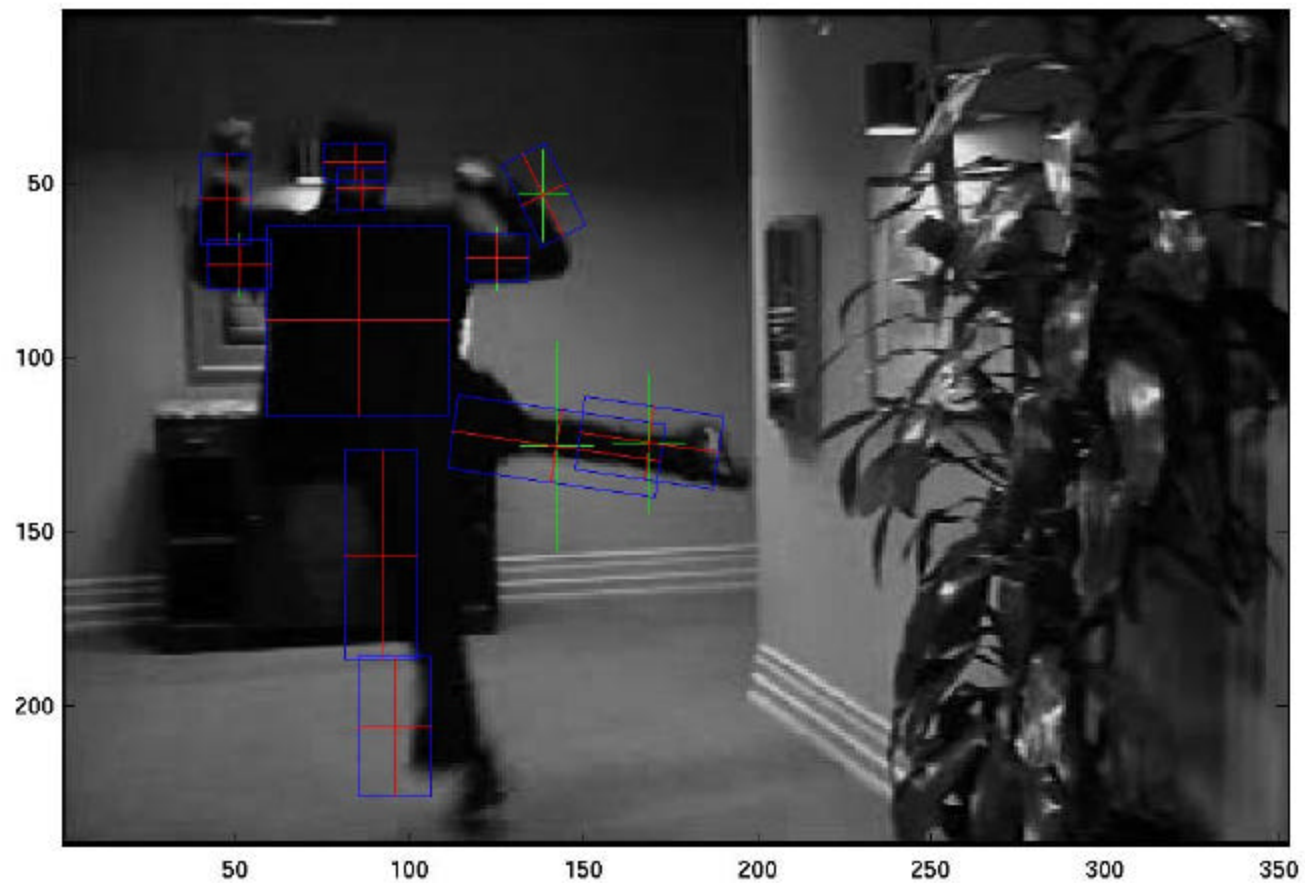
## Some of the possible body configurations:

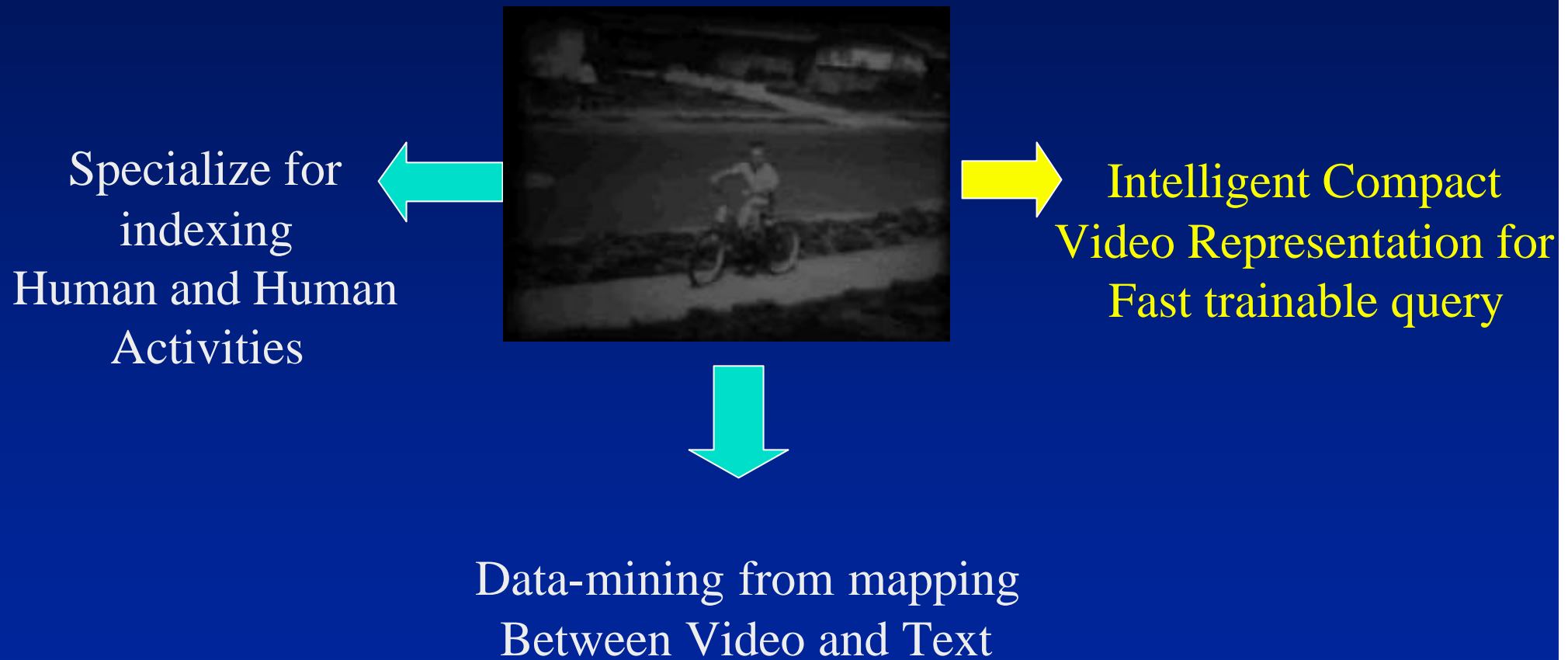
23



## Optimal configuration:

24





*Original  
Video  
Segment*

(3.4Mb)





Compute the transformation  
between image I and J, using  
affine approximation:

$$J(Ax+D) = I(x)$$

# Efficient Representation of Video

28

*Original  
Video  
Segment*

(3.4Mb)



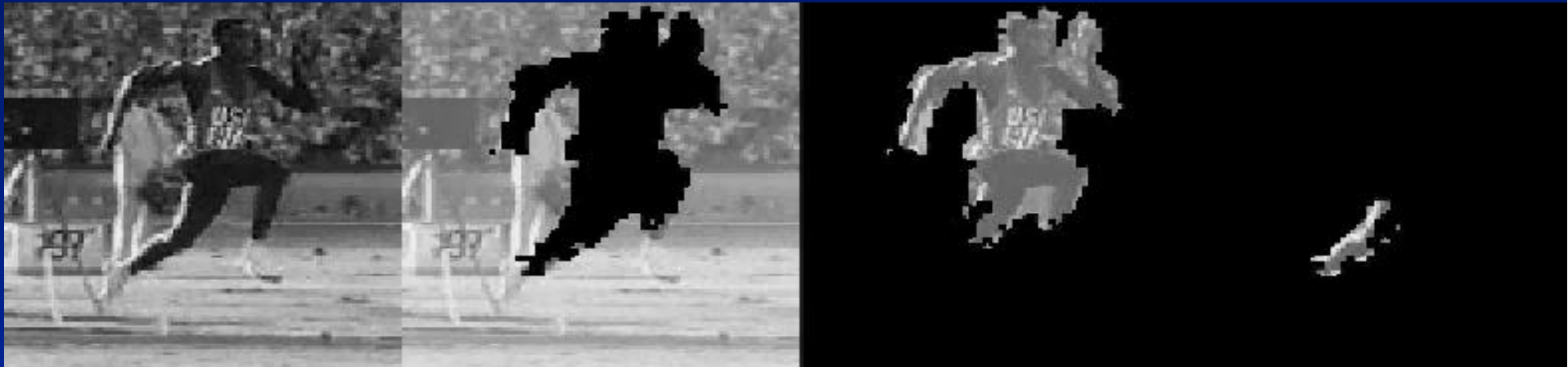
*Panorama Layer*

(35Kb)

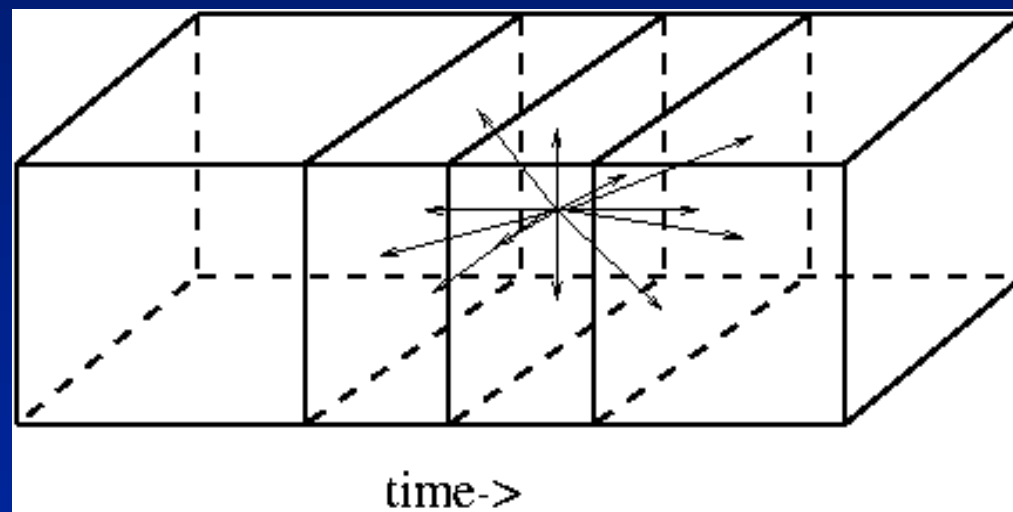


- Multiple object motion

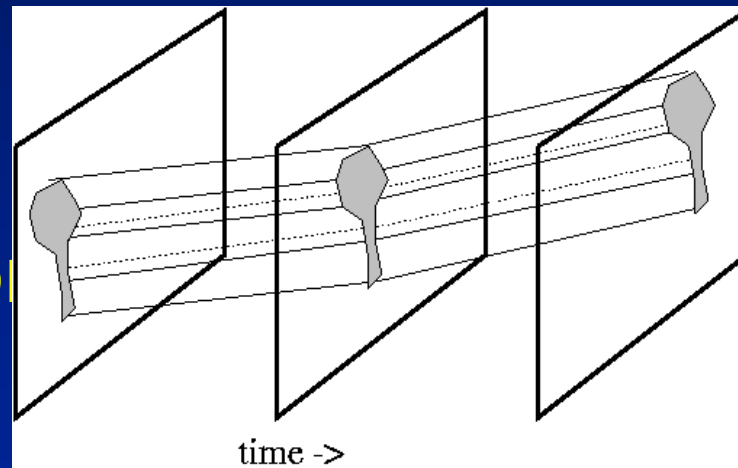




- Networks of spatial-temporal connections:  
Motion Segmentation with Normalized Cuts



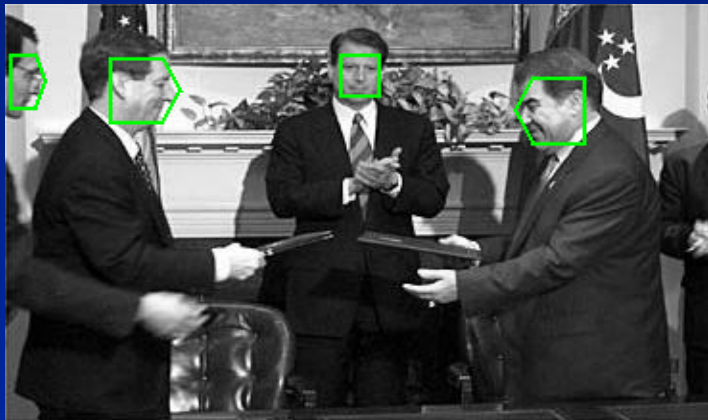
- Motion “proto-volume” in space-time



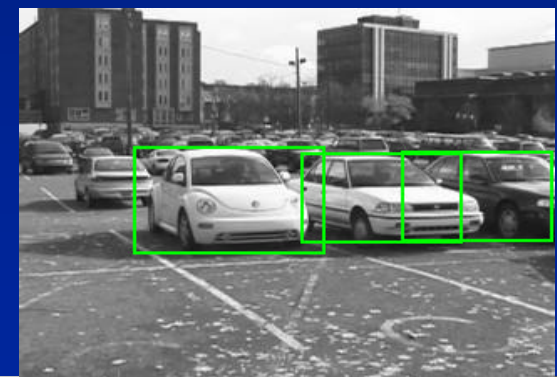
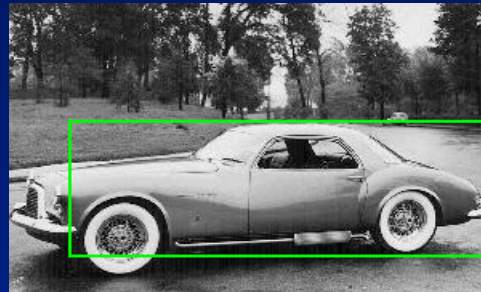
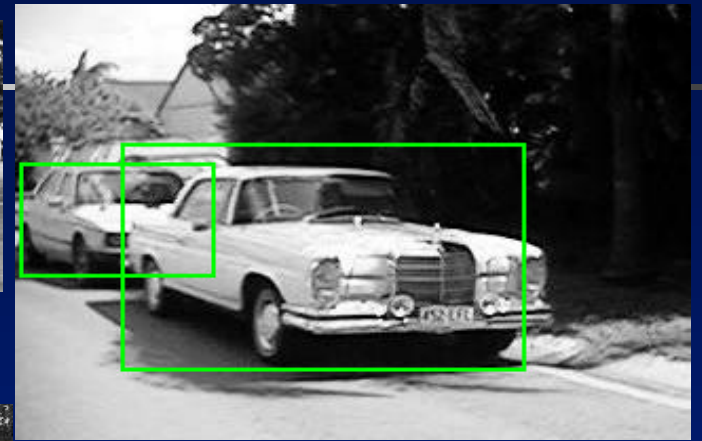
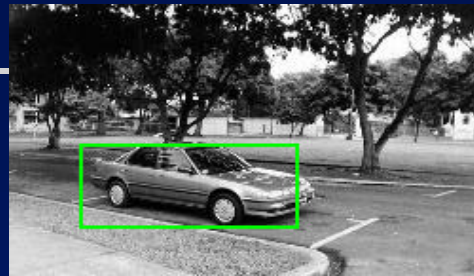
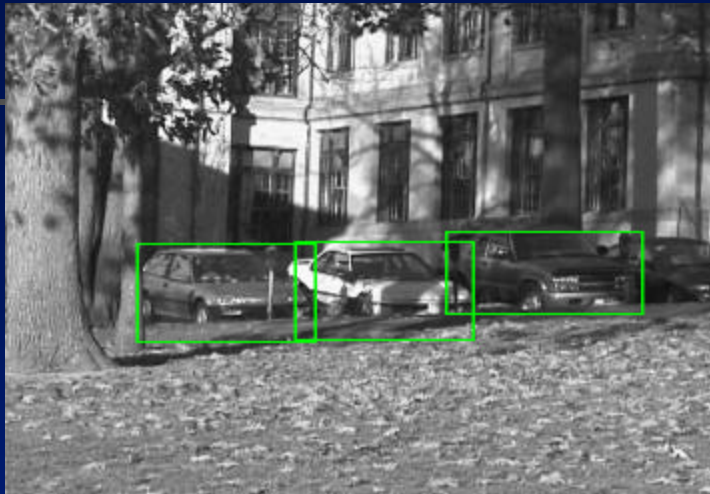
- Group co

## Rapid training of new objects in Video

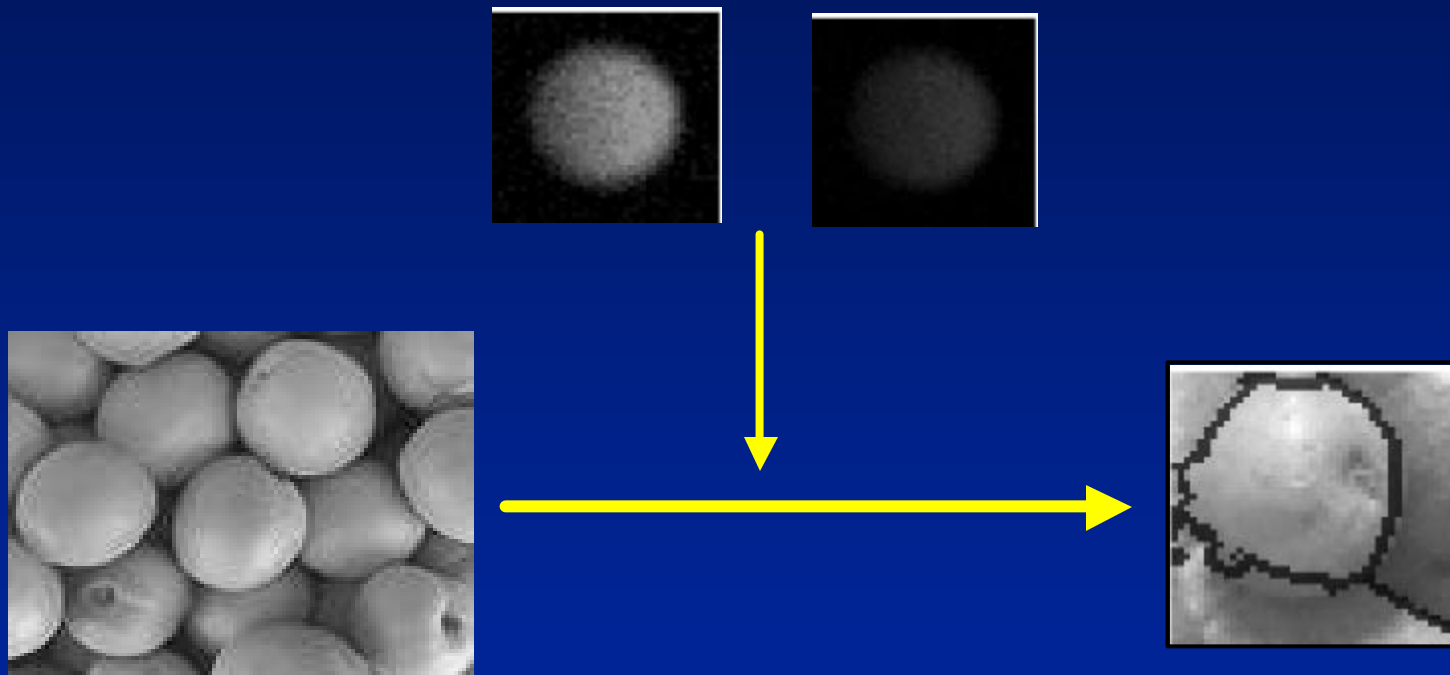
33



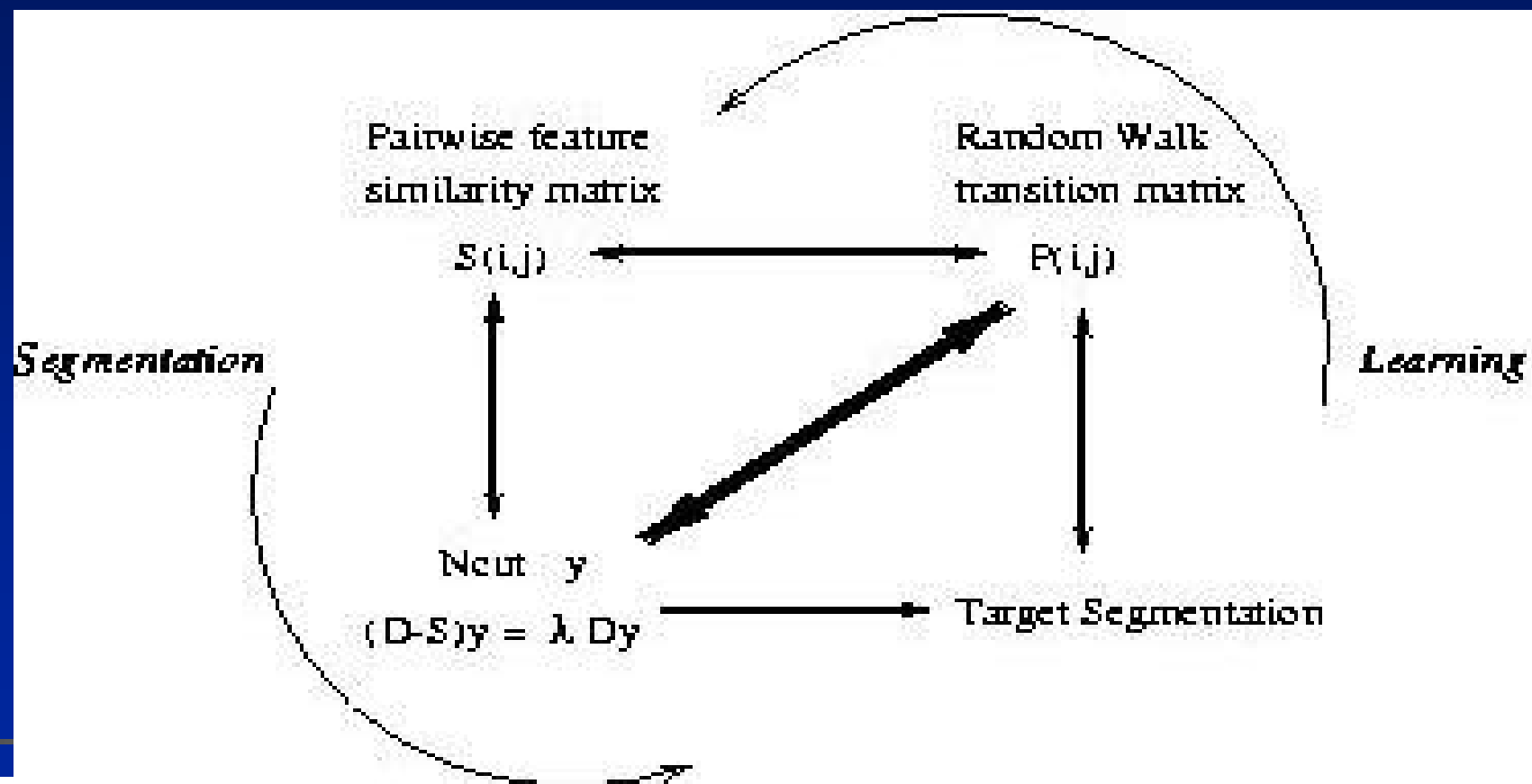
- Representation objects/scene at multiple level of abstraction
  - Low level motion, texture description
  - Mid level object segmentation
  - High level object type and instances



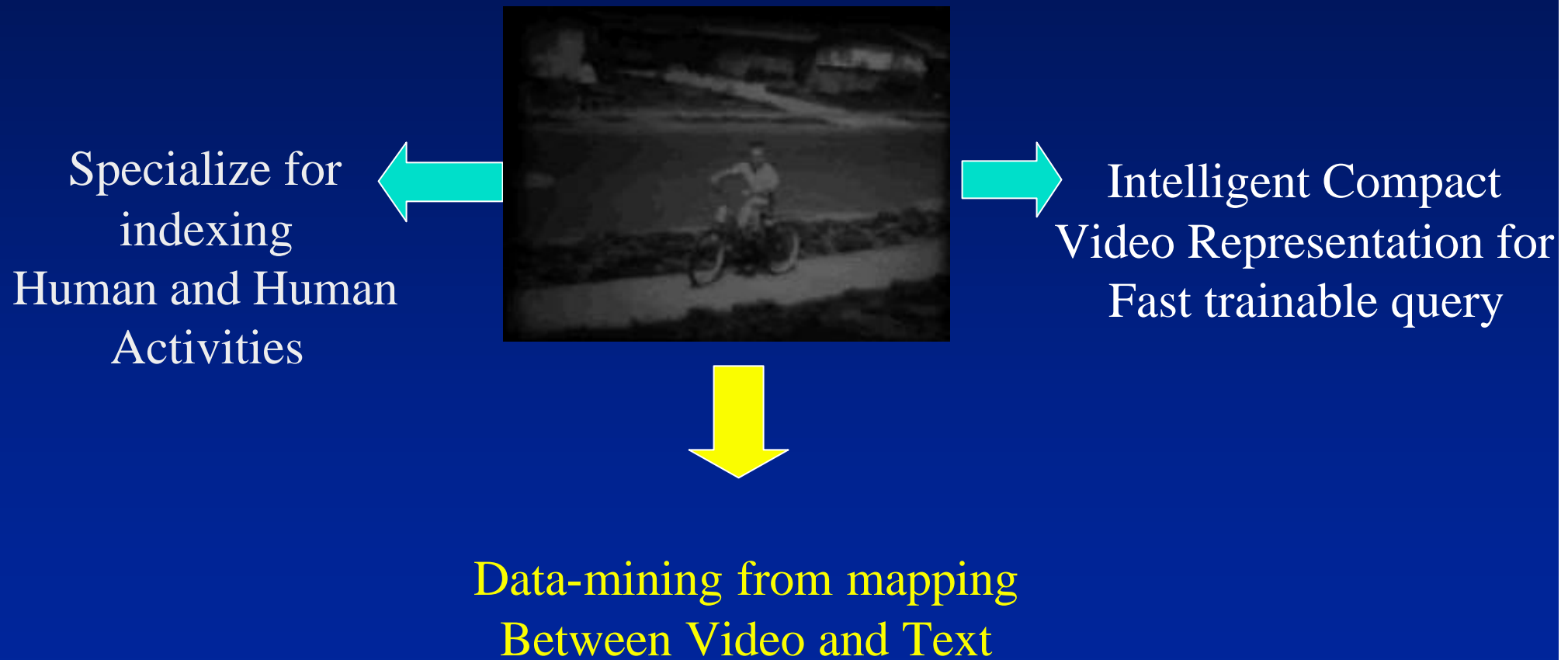




## Learning Seg. With Random Walk







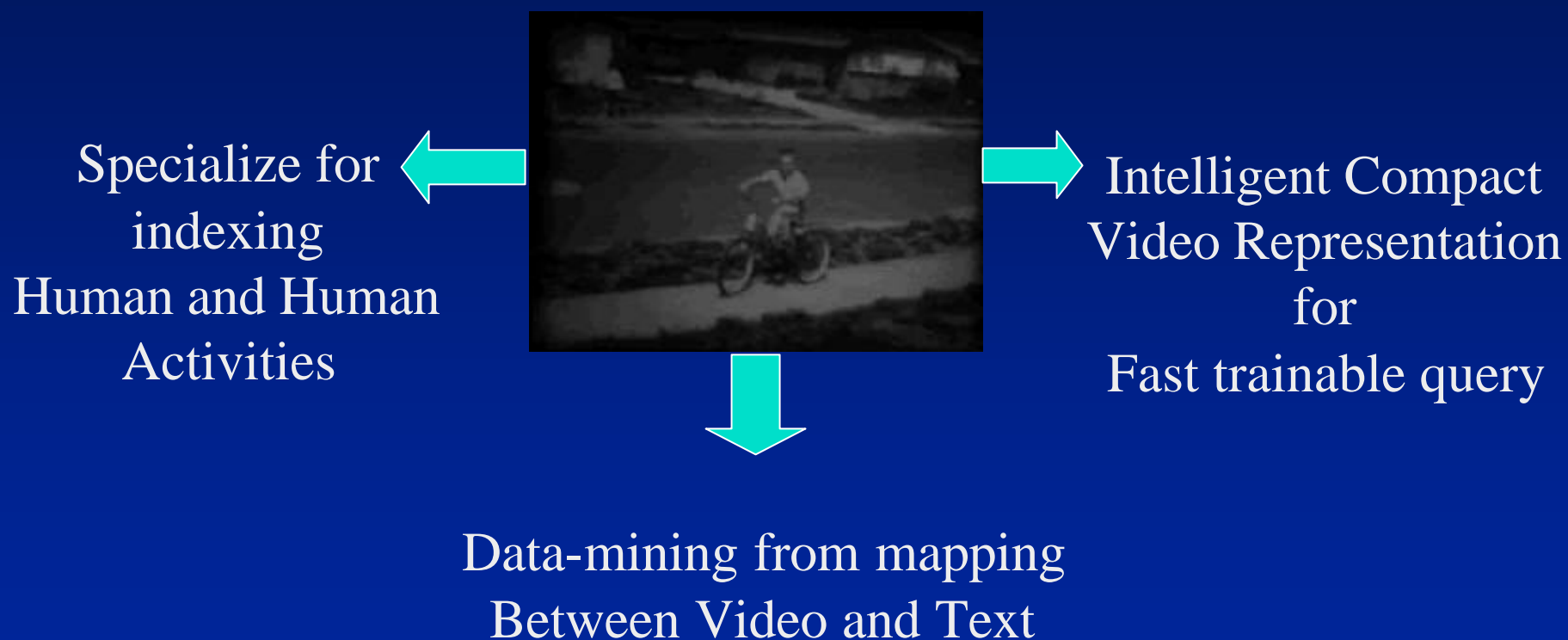
- Looking for cell phone images



- Keyword annotation is not sufficient
  - Too many objects
  - Disagreement of keywords



- Move towards more powerful image-query system in Video



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